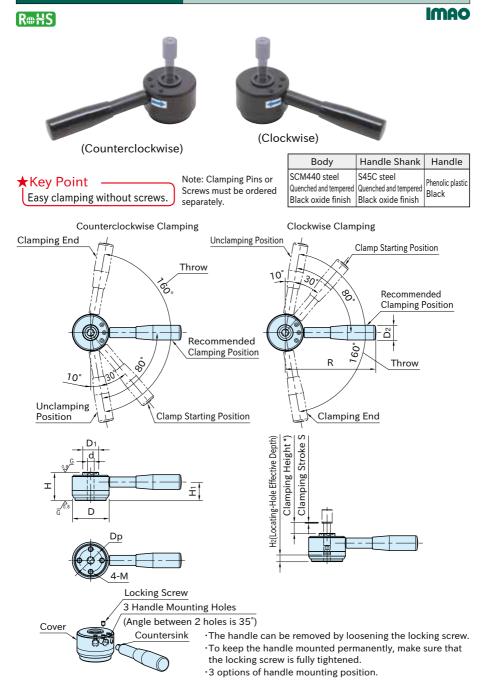
## QLPDH

## **PULL CLAMPS (Heavy)**



Part Number	Clamping Direction	S	d (F7)	H2	D1	H (±0.01)	D	М	Dp	R
QLPDH400R QLPDH400L	CW CCW	2	12	10	28	50	65	M 8×1.25 Depth 14	40	160
QLPDH500R	CW	2.5	16	12	34	63	80	M10×1.5 Depth 18	50	180

Part Number	D2	H1	Allowable Operating Load (N) **)	Clamping Force (kN)	Clamping Mechanism	Recommended Workpiece Thickness Tolerance ***)	Weight (kg)
QLPDH400R QLPDH400L	26	32.8	600	6	Spiral Cam	±0.5	1.2
QLPDH500R	28	41.1		8	Cam Angle: 4°	±0.8	2.2

\*) Grip length of QLPDH-X Clamping Pin (workpiece thickness)

\*\*) Allowable load to operate the handle

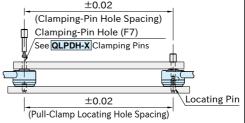
\*\*\*) Maintaining these recommended tolerances allows minimizing the variation of handle position in the clamping mode in clamping with the use of the Clamping P in.

\*\* \*) QLPDH500 is available only with Clockwise Clamping.

## How To Use ■ How to Locate Workpiece 1. Basic Method Ī CLAMPING PIN Locating Pin QLPDH-X ±0.02 (Clamping-Pin Hole Spacing) Clamping-Pin Hole (F7) See **QLPDH-X** Clamping Pins **Related Product**

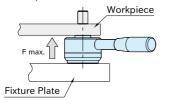
· QLPDH-X CLAMPING PINS (Heavy) ·QLPDH-M CLAMPING SCREWS(Heavy)

#### 2. Method for clamping and locating a workpiece at a time Give an accuracy shown below to the hole spacing to generate a locating accuracy of $\pm 0.08$ .



#### **Technical Information**

■ Allowable Loads in Machining of Workpiece Bottom Ensure that a force more than indicated below is not applied to the workpiece bottom.



Туре	Allowable Force To Workpiece Bottom (Per Clamp)				
QLPDH400	max. 8kN				
QLPDH500	max.14kN				

# **Performance Curve**

